# Recovery of a mixture of Gaussians by sum-of-norms clustering

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# Outline

## Sum-of-norms clustering

- (2) Recovery result of a mixture of Gaussians
- Cluster characterization theorem 3
- 4 Recovery theorem of a mixture of Gaussians



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# Clustering

Given *n* points  $a_1, a_2, ..., a_n$  lying in  $\mathbb{R}^d$ , one seeks to partition  $\{1, ..., n\}$  into *K* sets  $C_1, ..., C_K$  such that the  $a_i$ 's for  $i \in C_m$  are closer to each other than to the  $a_i$ 's for  $i \in C_{m'}$ ,  $m' \neq m$ .



Figure: Visualization of a possible clustering

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August 7, 2019 3 / 25

# Traditional clustering models

Here is a hierarchical clustering model

$$egin{array}{ll} \min_{x_1,\ldots,x_n\in {f R}^d} & rac{1}{2}\sum_{i=1}^n \|x_i-a_i\|^2 \ {
m subject to} & \sum_{i< j} 1_{x_i
eq x_j} \leq t \end{array}$$

Let  $x_1^*, x_2^*, ..., x_n^*$  be the optimizer of (1). For any distinct pair  $i, j \in \{1, 2, ..., n\}$ ,

- if  $x_i^* = x_i^*$ , points *i*, *j* are assigned to the same cluster;
- Otherwise, points *i*, *j* are assigned to different clusters;

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(1)

## Traditional clustering models

Here is a hierarchical clustering model

$$\begin{array}{ll} \min_{x_1,\ldots,x_n \in \mathbb{R}^d} & \frac{1}{2} \sum_{i=1}^n \|x_i - a_i\|^2 \\ \text{subject to} & \sum_{i < j} 1_{x_i \neq x_j} \le t \end{array}$$

#### Remark

• If  $t \ge \frac{n(n-1)}{2}$ , (1) is unconstrained and  $x_i^* = a_i$  for all  $i \in \{1, 2, ..., n\}$ ; • If  $t = \frac{n(n-1)}{2} - 1$ , one distinct pair  $i, j \in \{1, 2, ..., n\}$  is forced to fuse; • If t = 0,  $x_i^* = \sum_{i=1}^n \frac{a_i}{n}$ .

Problems of traditional clustering models:

- Most are hard combinatorial optimization problems;
- Prior knowledge about the number of clusters is often required;
- Initialization affects the clustering assignment.

## A convex clustering model

Hocking et al. (2011) proposed the following convex relaxation of the Hierarchical clustering model.

$$\min_{\substack{x_1, \dots, x_n \in \mathbb{R}^d \\ \text{subject to}}} \quad \frac{1}{2} \sum_{i=1}^n \|x_i - a_i\|^2$$

$$\sum_{i < j} \|x_i - x_j\| \le t$$

$$(2)$$

Here is the Lagrangian formulation of (2).

$$\min_{x_1,...,x_n \in \mathbb{R}^d} \frac{1}{2} \sum_{i=1}^n \|x_i - a_i\|^2 + \lambda \sum_{i < j} \|x_i - x_j\|.$$

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Recovery of a mixture of Gaussians by sum-of

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## A convex clustering model

$$\min_{x_1,...,x_n \in \mathbb{R}^d} \frac{1}{2} \sum_{i=1}^n \|x_i - a_i\|^2 + \lambda \sum_{i < j} \|x_i - x_j\|.$$
(3)

The formulation (3) is known as sum-of-norms clustering, convex clustering, or clusterpath clustering.

## Remark

The formulation (3) is strongly convex.

Let  $x_1^*, x_2^*, ..., x_n^*$  be the optimizer of (3). For any distinct pair  $i, j \in \{1, 2, ..., n\}$ ,

- if  $x_i^* = x_i^*$ , points *i*, *j* are assigned to the same cluster;
- Otherwise, points *i*, *j* are assigned to different clusters;

- Setup: Given K Gaussians with means  $\mu_1, \ldots, \mu_K \in \mathbb{R}^d$ , variances  $\sigma_1^2, \ldots, \sigma_K^2$ , and probabilities  $w_1, \ldots, w_K$ , positive and summing to 1.
- Generative model: One draws n i.i.d. samples from K Gaussians.
  - An index m ∈ {1,..., K} is selected at random according to probabilities w<sub>1</sub>,..., w<sub>K</sub>,
  - A point *a* is chosen according to the spherical Gaussian distribution  $N(\mu_m, \sigma_m^2 I)$ .

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# Recovery condition by Panahi et al. (2017)

## Recovery condition (Panahi et al., 2017)

For the appropriate choice of  $\lambda$ , sum-of-norms clustering formulation (3) exactly recovers a mixture of Gaussians provided that for all m, m',  $1 \le m < m' \le K$ ,

$$\|\mu_m - \mu_{m'}\| \ge \frac{CK\sigma_{\max}}{w_{\min}} \operatorname{polylog}(n).$$
(4)

- C: some constant
- K: the number of Gaussians
- polylog(n): a polynomial function with respect to log(n)
- $\sigma_{max}$ :  $max\{\sigma_1, \sigma_2, ..., \sigma_K\}$
- $w_{min}$ :  $min\{w_1, w_2, ..., w_K\}$

# Recovery condition by Panahi et al. (2017)

$$\|\mu_{m} - \mu_{m'}\| \geq \frac{CK\sigma_{\max}}{w_{\min}} \operatorname{polylog}(n).$$

#### Remark

As the number of samples n tends to infinity, the bound implies that distinguishing the clusters becomes increasingly difficult





Figure: 2D Gaussians with 1000 samples

Figure: polylog(n) VS n

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August 7, 2019 11 / 25

# Main contributions

We prove (3) can correctly cluster the points lying within some fixed number ( $\theta$ ) of standard-deviations for each mean even as  $n \to \infty$ .



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August 7, 2019 12 / 25

# Our recovery condition

Define 
$$V_m = \{a_i : \|a_i - \mu_m\| \le \theta \sigma_m\}, \quad m = 1, \dots, K.$$

#### Recovery condition

There is a  $\lambda$  such that with probability tending to 1 exponentially fast in *n*, the points in  $V_m$  are in the same cluster for any  $m = 1, \ldots, K$ , and these clusters are distinct, provided that

$$\min_{1 \le m < m' \le \kappa} \|\mu_m - \mu_{m'}\| > \frac{4\theta\sigma_{\max}}{F(\theta, d)w_{\min} - \epsilon}.$$
(5)

- \* *d*: the dimension of the data space
- θ: the number of standard-deviations from the mean

- \*  $\epsilon > 0$ : an arbitrary number
- F(θ, d) denotes the cumulative density function of the chi distribution with d degrees of freedom

## Our recovery condition

$$\min_{1 \le m < m' \le \kappa} \|\mu_m - \mu_{m'}\| > \frac{4\theta\sigma_{\max}}{F(\theta, d)w_{\min} - \epsilon}$$

## Remark

The dependence of the right-hand side on n as well as the factor of K has been removed.

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## Cluster characterization theorem by Chiquet et al. (2017)

Let  $x_1^*, \ldots, x_n^*$  denote the optimizer of (3). Let  $x^* := \begin{vmatrix} x_1 \\ x_2^* \\ x_n^* \end{vmatrix} \in \mathbb{R}^{nd}$ .

Suppose  $\emptyset \neq C \subseteq \{1, \ldots, n\}$ .

## (a) Necessary condition

If for some  $\hat{x} \in \mathbb{R}^d$ ,  $x_i^* = \hat{x}$  for  $i \in C$  and  $x_i^* \neq \hat{x}$  for  $i \notin C$ , then there exist  $z_{ij}^*$  for  $i, j \in C$ ,  $i \neq j$ , which solve

$$a_{i} - \frac{1}{|C|} \sum_{l \in C} a_{l} = \lambda \sum_{j \in C - \{i\}} z_{ij}^{*} \quad \forall i \in C,$$

$$\|z_{ij}^{*}\| \leq 1 \qquad \forall i, j \in C, i \neq j,$$

$$z_{ij}^{*} = -z_{ji}^{*} \qquad \forall i, j \in C, i \neq j.$$
(6)

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# Cluster characterization theorem by Chiquet et al. (2017)

Suppose 
$$\emptyset \neq C \subseteq \{1, \ldots, n\}$$
.

## (b) Sufficient condition

Suppose there exists a solution  $z_{ij}^*$  for  $j \in C - \{i\}$ ,  $i \in C$  to the following conditions.

$$\begin{aligned} \mathsf{a}_{i} &- \frac{1}{|\mathcal{C}|} \sum_{l \in \mathcal{C}} \mathsf{a}_{l} = \lambda \sum_{j \in \mathcal{C} - \{i\}} z_{ij}^{*} \quad \forall i \in \mathcal{C}, \\ & \left\| z_{ij}^{*} \right\| \leq 1 \qquad \forall i, j \in \mathcal{C}, i \neq j, \\ & z_{ij}^{*} = -z_{ji}^{*} \qquad \forall i, j \in \mathcal{C}, i \neq j. \end{aligned}$$

Then there exists an  $\hat{x} \in \mathbb{R}^d$  such that the minimizer  $x^*$  of (3) satisfies  $x_i^* = \hat{x}$  for  $i \in C$ .

16 / 25

# Cluster characterization theorem by Chiquet et al. (2017)

With the cluster chracterization theorem,

- one can chacterize the cluster assignment without the information of other points;
- one can prove the agglomeration property of sum-of-norms clustering with unitary weight (conjectured by Hocking et al. (2011)).

Consider a  $\bar{\lambda} \ge \lambda$  and its corresponding sum-of-norms cluster model:

$$\min_{x_1,...,x_n} \frac{1}{2} \sum_{i=1}^n \|x_i - a_i\|^2 + \bar{\lambda} \sum_{i < j} \|x_i - x_j\|.$$
(7)

## Corollary (Chiquet et al., 2017)

If there is a *C* such that minimizer  $x^*$  of (3) satisfies  $x_i^* = \hat{x}$  for  $i \in C$ ,  $x_i^* \neq \hat{x}$  for  $i \notin C$  for some  $\hat{x} \in \mathbb{R}^d$ , then there exists an  $\hat{x}' \in \mathbb{R}^d$  such that the minimizer of (7),  $\bar{x}^*$ , satisfies  $\bar{x}_i^* = \hat{x}'$  for  $i \in C$ .

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August 7, 2019 17 / 25

## Recovery of a mixture of Gaussians theorem

Let the vertices  $a_1, \ldots, a_n \in \mathbb{R}^d$  be generated from a mixture of KGaussian distributions with parameters  $\mu_1, \ldots, \mu_K$ ,  $\sigma_1^2, \ldots, \sigma_K^2$ , and  $w_1, \ldots, w_K$ . Let  $\theta > 0$  be given, and let

$$V_m = \{a_i : \|a_i - \mu_m\| \le \theta \sigma_m\}, \quad m = 1, \dots, K.$$

Let  $\epsilon > 0$  be arbitrary.



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Recovery of a mixture of Gaussians by sum-of

#### Theorem (Lower Bound)

For any m = 1, ..., K, with probability exponentially close to 1 (and depending on  $\epsilon$ ) as  $n \to \infty$ , for the solution  $x^*$  computed by (3), the points in  $V_m$  are in the same cluster provided

$$\lambda \geq \frac{2\theta\sigma_m}{(F(\theta,d)w_m-\epsilon)n}.$$

(8)

\*  $F(\theta, d)$ : the cumulative density function of the chi distribution with d degrees of freedom.

## Theorem (Upper Bound)

Furthermore, the cluster associated with  $V_m$  is distinct from the cluster associated with  $V_{m'}$ ,  $1 \le m < m' < k$ , provided that

$$\lambda < \frac{\|\mu_m - \mu_{m'}\|}{2(n-1)}.\tag{9}$$

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Provided that

$$\frac{2\theta\sigma_m}{(F(\theta,d)w_m-\epsilon)n} < \frac{\|\mu_m-\mu_{m'}\|}{2(n-1)},$$

there exists a  $\lambda$  so that the solution to (3) can simultaneously place all points in  $V_m$  into the same cluster for each  $m = 1, \ldots, K$  while distinguishing the clusters.

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21 / 25

- The key technique is the cluster characterization theorem, which decouples the clusters from each other so that each can be analyzed in isolation.
- The analysis can be extended to Gaussians with a more general covariance matrix, uniform distributions and many kinds of deterministic distributions.
- The cluster characterization theorem does not apply to most other clustering algorithms, or even to sum-of-norm clustering in the case of unequal weights.

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